

UNITED STATES PATENT AND TRADEMARK OFFICE
CERTIFICATE OF CORRECTION

PATENT NO. : 7,736,394
APPLICATION NO. : 10/721,764
ISSUE DATE : June 15, 2010
INVENTOR(S) : Stephane Bedard, et al.

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It is certified that error appears in the above-identified patent and that said Letters Patent is hereby corrected as shown below:

In Column 1, Line 10 (Approx.), Change “2002 ;” to --2002;--.

In Column 1, Line 11 (Approx.), Change “2002 ;” to --2002;--.

In Column 2, Lines 9-10, After “member;” delete “a socket connector assembly for connecting a socket to said primary joint member;” and insert the same on Line 10, Col. 2 as a new paragraph.

In Column 3, Line 51, Delete “FIGS. 15 to 21 show the inverted actuator configuration.” and insert the same on Line 50, Col. 3 after “configuration.” as a continuation of the paragraph.

In Columns 4-5, Lines 63-67 (Col.4) and 1-2 (Col. 5), Delete “These bumpers (44) can be, for example, bumper model GBA-1 manufactured by Tecspak Inc. Of course, other types of bumpers (44) may be used as well. They are mounted on corresponding brackets (42) located on the side and the front of the upper plate (26) of the knee member (12). The brackets (42) are also used to support connectors (78) which are described later in the description.” and insert the same on Line 62, Col. 4 after “range motion.” as a continuation of the paragraph.

In Column 5, Line 22, Change “26cm” to --26 cm--.

In Column 5, Line 42, Change “80and” to --80 and--.

In Columns 6-7, Lines 66-67 (Col. 6) and 1-3 (Col. 7), Delete “Connectors (78), attached to the brackets (42) of the knee member (12), provide the required connections. A similar connector (78) is provided on the motor (70). A two-part wire clamp (39A, 39B) on parts (254) allows to hold the wire on the support (38).” and insert the same on Line 65, Col. 6 after “thereof.” as a continuation of the paragraph.

In Column 7, Line 64, Change “E2-512-250-i” to --E2-512-250-I--.

In Column 8, Line 3, Change “1 K” to --1K--.

In Column 11, Line 48, Change “br” to --br--.

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DOCKET NO. OSSUR.901CP1

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In Column 11, Line 65, Change " $\theta_{fix} = \pi - \pi - \theta_K - \beta$ " to " $\theta_{fix} = \pi - \alpha - \theta_K - \beta$ ".

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